

# SYMPLECTIC GEOMETRY, LECTURE 7

Prof. Denis Auroux

## 1. FLOER HOMOLOGY

For a Hamiltonian diffeomorphism  $f : (M, \omega) \rightarrow (M, \omega)$ ,  $f = \phi_H^1$ ,  $H_t : M \rightarrow \mathbb{R}$  1-periodic in  $t$ , we want to look for fixed points of  $f$ , i.e. 1-periodic orbits of  $X_H$ ,  $x'(t) = X_{H_t}(x(t))$ . We consider the Floer complex  $CF^*(f)$ , whose basis are 1-periodic orbits; these correspond to critical points of the action functional  $\mathcal{A}_H$  on a covering of the free loop space  $\Omega(M)$ . The differential 'counts' solutions of Floer's equations

$$(1) \quad u : \mathbb{R} \times S^1 \rightarrow M, \quad \frac{\partial u}{\partial s} + J(u(s, t)) \left( \frac{\partial u}{\partial t} - X_{H_t}(u) \right) = 0$$

such that  $\lim_{s \rightarrow \pm\infty} u(s, \cdot) = x_{\pm}$  (1-periodic orbits). The solutions are formal gradient flow lines of  $\mathcal{A}_H$  between the critical points  $x_{\pm}$ .

**Theorem 1** (Arnold's conjecture). *If the fixed points of  $f$  are nondegenerate, then  $\#\text{Fix}(f) \geq \sum_i \dim H^i(M)$ , i.e.  $\#\text{Fix}(f) = \text{rk } CF^* \geq \text{rk } HF^* = \text{rk } H^*(CF^*, \partial) = \text{rk } H^*(M)$ .*

**1.1. Lagrangian intersections.** There is a notion of Lagrangian Floer homology, which is not always defined (in fact, there are explicit obstructions to its existence). The idea is to count intersections of Lagrangian submanifolds  $L, L' \subset M$  in a manner which is invariant under Hamiltonian deformations (isotopies). Assume that  $L$  and  $L'$  are transverse (if not, e.g. when  $L = L'$ , replace the submanifold  $L$  by the graph  $L_t$  of an exact 1-form in  $T^*L$ ). To define Floer homology, one defines a complex  $CF^*(L, L')$  whose basis is the set of intersection points, and whose differential is given by  $\partial p = \sum_q n_{p,q} q$ , where  $n_{p,q}$  counts solutions to

$$(2) \quad u : \mathbb{R} \times [0, 1] \rightarrow M, \quad u(\mathbb{R} \times 0) \subset L, \quad u(\mathbb{R} \times 1) \subset L', \quad \frac{\partial u}{\partial s} + J \frac{\partial u}{\partial t} = 0$$

Under suitable assumptions, one finds that  $\partial^2 = 0$ , giving us a Floer homology

$$(3) \quad HF^*(L, L') = H^*(CF^*(L, L'), \partial)$$

which is invariant under Hamiltonian deformations of  $L, L'$ . Moreover,  $\text{rk } HF^* \leq \text{rk } CF^* = |L \cap L'|$ .

**Theorem 2** (Floer, Oh, Fukaya-Oh-Ohta-Ono). *Given a compact Lagrangian submanifold  $L \subset M$  which is "relatively spin" (i.e.  $w_2(TL) \in \text{Im}\{i^* : H^2(M, \mathbb{Z}/2\mathbb{Z}) \rightarrow H^2(L, \mathbb{Z}/2\mathbb{Z})\}$ ) s.t.  $i_* : H_1(L, \mathbb{Q}) \rightarrow H_1(M, \mathbb{Q})$  is injective, then  $\forall \psi \in \text{Ham}(M, \omega)$  s.t.  $\psi(L)$  intersects  $L$  transversely,  $\#(L \cap \psi(L)) \geq \sum \dim H_i(L, \mathbb{Q})$ .*

*Remark.* Applying this theorem to the diagonal  $\Delta = \Delta(M) \subset M \times M$  and the graph of a Hamiltonian diffeomorphism  $f$  on  $M$ , one recovers Arnold's conjecture.

## 2. ALMOST-COMPLEX STRUCTURES

To begin, we will study complex structures on vector spaces.

**Definition 1.** *A complex structure on a vector space  $V$  is an endomorphism  $J : V \rightarrow V$  s.t.  $J^2 = -I$ . Thinking of this  $J$  as multiplication by  $i$  turns  $V$  into a complex vector space,  $(x + iy)v = xv + yJv$ . If  $V$  is a symplectic vector space with symplectic form  $\Omega$ , a complex structure is compatible if  $G(u, v) = \Omega(u, Jv)$  is a positive symmetric inner product. Note that being symmetric is equivalent to  $\Omega(Ju, Jv) = \Omega(u, v)$ , and being positive is precisely  $\Omega(u, Ju) > 0 \forall u \neq 0$ .*

*Example.* Let  $V = (\mathbb{R}^{2n}, \Omega_0)$  be the standard symplectic vector space, with standard basis  $e_1, \dots, e_n, f_1, \dots, f_n$ , and define  $J_0$  by  $e_i \mapsto f_i, f_i \mapsto -e_i$ . Then

$$(4) \quad J_0^2 = -\text{id}, G_0(u, v) = \Omega_0(u, J_0 v) \implies G_0(e_i, e_i) = 1, G_0(f_i, f_i) = 1$$

and all other pairings are 0. In matrix terms,  $\Omega_0 = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}$ , and  $J_0 = \begin{pmatrix} 0 & -I \\ I & 0 \end{pmatrix}$ , so  $G_0 = \Omega_0 J_0 = I$ .

This gives us a natural isomorphism with  $\mathbb{C}^n$ .

**Proposition 1.** *If  $(V, \Omega)$  is a symplectic vector space,  $\exists$  a compatible  $J$ . Moreover, given any positive inner product  $\langle \cdot, \cdot \rangle$  on  $V$ , we can build an  $\Omega$ -compatible complex structure on  $V$  canonically (though it has no direct relation to the given inner product).*

*Proof.* For the first part, taking  $J = J_0$  in a standard basis gives the desired endomorphism. For the second part, by the nondegeneracy of  $\Omega$ , we have isomorphisms  $u \mapsto \Omega(u, \cdot)$  and  $u \mapsto \langle u, \cdot \rangle$  from  $V$  to  $V^*$ . We thus obtain an endomorphism  $A = \langle \cdot, \cdot \rangle^{-1} \circ \Omega$  s.t.  $\Omega(u, v) = \langle Au, v \rangle$ .  $A$  is invertible and skew-symmetric w.r.t.  $\langle \cdot, \cdot \rangle$ , i.e.  $A^* = -A$  (since  $\Omega(v, u) = \langle Av, u \rangle = \langle v, A^* u \rangle = \langle A^* u, v \rangle = -\Omega(u, v) = -\langle Au, v \rangle$ ). Thus,  $AA^* = -A^2$  is symmetric and positive definite, therefore diagonalizable with real, strictly positive eigenvalues. This implies the existence of a square root  $\sqrt{AA^*} (= \text{diag}(\sqrt{\lambda_i}))$ , so define  $J = (\sqrt{AA^*})^{-1} A$ . (Note that the decomposition  $A = \sqrt{AA^*} J$  gives a "polar decomposition" of  $A$ .)  $A$  commutes with  $\sqrt{AA^*}$ : letting  $V_i$  be the eigenspace of  $AA^*$  with eigenvalue  $\lambda_i$ , or similarly that of  $\sqrt{AA^*}$  with eigenvalue  $\sqrt{\lambda_i}$ , we find that,

$$(5) \quad \forall v \in V_i, (AA^*)Av = -A^3 v = A(AA^*)v = \lambda_i Av \implies Av \in V_i$$

So  $J$  also commutes with  $A$  and with  $\sqrt{AA^*}$ , and thus is skew-symmetric

$$(6) \quad J^* = A^*(\sqrt{AA^*})^{-1} = -A(\sqrt{AA^*})^{-1} = -J$$

and orthogonal

$$(7) \quad J^* J = A^*(\sqrt{AA^*})^{-1} (\sqrt{AA^*})^{-1} A = \text{id}$$

In particular,  $J^2 = -J^* J = -\text{id}$ . For compatibility, note that

$$(8) \quad \begin{aligned} \Omega(Ju, Jv) &= \langle AJu, Jv \rangle = \langle JAu, Jv \rangle = \langle Au, v \rangle = \Omega(u, v) \\ \Omega(u, Ju) &= \langle Au, Ju \rangle = \langle -JAu, u \rangle = \langle -(\sqrt{AA^*})^{-1} AAu, u \rangle \\ &= \langle (\sqrt{AA^*})^{-1} (AA^*)u, u \rangle = \langle (\sqrt{AA^*})u, u \rangle > 0 \end{aligned}$$

thus completing the proof.  $\square$

*Remark.* Note that  $G(u, v) = \Omega(u, Jv) = \langle \sqrt{AA^*}u, v \rangle$ , so if  $\langle \cdot, \cdot \rangle$  was already compatible with  $\Omega$ , then  $AA^* = I, J = A, G = \langle \cdot, \cdot \rangle$ .

**Definition 2.** *An almost-complex structure on a manifold  $M$  is  $J \in \text{End}(TM)$  s.t.  $J^2 = -I$  (i.e.  $\forall x \in M, J_x$  is a complex structure on  $T_x M$ ). If  $M = (M, \omega)$  is a symplectic manifold,  $J$  is compatible if  $\forall x \in M, J_x$  is  $\omega_x$ -compatible, with associated Riemannian metric  $g_x(u, v) = \omega_x(u, J_x v)$ . We say that  $(\omega, g, J)$  is a compatible triple, with any two determining the third.*