

18.034, Honors Differential Equations
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Recitation Suggestions
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Next time I will prove the generalized eigenspaces give a direct sum decomposition. Then I will explain Jordan normal form and how this gives the complete solution of a linear system of 1st order ODE's over \mathbb{C} (and then explain what needs to be done \mathbb{R}).

Until then, please keep doing examples of finding generalized eigenvectors and using the usual eigenvectors in simple cases (i.e. when generalized eigenspaces = eigenspaces) to solve systems of 1st order ODE's.

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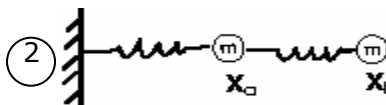
Examples: ① $y' = \begin{pmatrix} a & b \\ -b & a \end{pmatrix} y$. $p_A(\lambda) = (\lambda - a)^2 + b^2$, $\lambda = a \pm bi$

$\lambda = a + bi$: $v = \begin{pmatrix} 1 \\ i \end{pmatrix}$; $\lambda = a - bi$: $v = \begin{pmatrix} 1 \\ -i \end{pmatrix}$.

$y = A \begin{pmatrix} 1 \\ i \end{pmatrix} e^{at} e^{ibt} + B \begin{pmatrix} 1 \\ -i \end{pmatrix} e^{at} e^{-ibt}$

$\rightsquigarrow y = C_1 \begin{pmatrix} \cos(bt) \\ -\sin(bt) \end{pmatrix} e^{at} + C_2 \begin{pmatrix} \sin(bt) \\ \cos(bt) \end{pmatrix} e^{at}$

x_a and x_b are "reduced" coords.
 incorporating natural equilibrium
 displacement of the springs.

②  $m x_a'' = -k x_a + k(x_b - x_a)$ $v_a = x_a'$
 $m x_b'' = -k(x_b - x_a)$ $v_b = x_b'$

$$\begin{pmatrix} x_a \\ v_a \\ x_b \\ v_b \end{pmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ \frac{-2k}{m} & 0 & \frac{k}{m} & 0 \\ 0 & 0 & 0 & 1 \\ \frac{k}{m} & 0 & \frac{k}{m} & 0 \end{bmatrix} \begin{pmatrix} x_a \\ v_a \\ x_b \\ v_b \end{pmatrix}$$

$T_r = 0$, $\det = \left(\frac{k}{m}\right)^2$, $p_A(\lambda) = \lambda^4 + 3\left(\frac{k}{m}\right)\lambda^2 + \left(\frac{k}{m}\right)^2$, $\omega^2 = \left(\frac{k}{m}\right)$, then

$\lambda = \pm i \sqrt{\frac{3 + \sqrt{5}}{2}} \omega$, $\pm i \sqrt{\frac{3 - \sqrt{5}}{2}} \omega$. If $\lambda^2 = -\left(\frac{3 \pm \sqrt{5}}{2}\right) \frac{k}{m}$, then eigenvector is $\begin{pmatrix} 2 \\ 2\lambda \\ 1 \pm \sqrt{5} \\ (1 \pm \sqrt{5}\lambda) \end{pmatrix}$.

Interesting result: For the "normal modes" x_b and x_a are either in phase or 180° out of phase.