

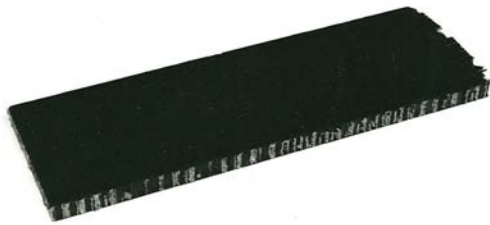
Sandwich Panels

- two stiff strong skins separated by a light weight core
- separation of skins by core increases moment of inertia, with little increase in weight
- efficient for resisting bending + buckling
- like an I beam: faces = flanges - carry normal stress
core = web - carries shear stress
- examples: engineering + nature

- faces: composites, metals
- cores: honeycombs, foams, balsa
- honeycombs: lighter than foam cores for req'd stiffness, strength
- foams: heavier, but can also provide thermal insulation
- mechanical behaviour depends on face + core properties + on geometry
- typically, panel must have some required stiffness and/or strength
- often, want to minimize weight - optimization problem
eg. refrigerated vehicles; sporting equipment (sail boats, skis)



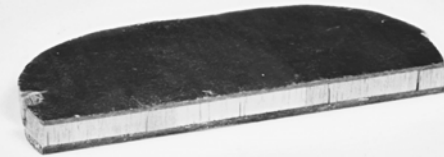
(a)



(b)



(a)



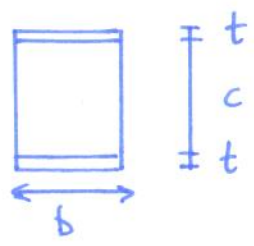
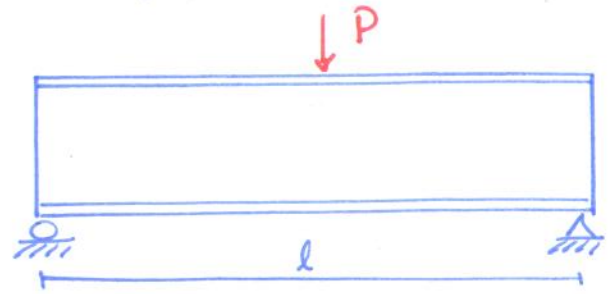
(b)



Figure removed due to copyright restrictions. See Figure 9.4: Gibson, L. J. and M. F. Ashby. *Cellular Solids: Structure and Properties*. Cambridge University Press, 1997.

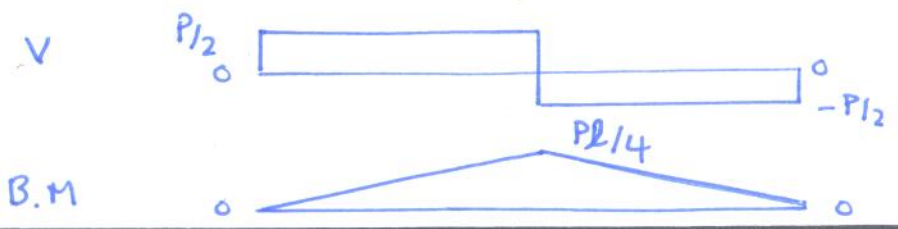
Sandwich beam stiffness

• analyze beams here (simpler than plates; some ideas apply)



Face: ρ_f, E_f, σ_{yf}
 Core: $\rho_c^*, E_c^*, \sigma_c^*$
 (Solid: ρ_s, E_s, σ_{ys})

Typically $E_c^* \ll E_f$



$\delta = \delta_b + \delta_s$: bending deflection δ_b + shear deflⁿ (of core) δ_s

since $G_c^* \ll E_f$, core shear deflections significant

$$\delta_b = \frac{Pl^3}{B_1 (EI)_{eq}}$$

$B_1 = \text{constant, depending on loading configuration}$
 3 pt bend, $B_1 = 48$

$$(EI)_{eq} = \left(\frac{E_f bt^3}{12} \times 2 \right) + E_c \frac{bc^3}{12} + E_f bt \left(\frac{c+t}{2} \right)^2 \quad \text{parallel axis theorem}$$

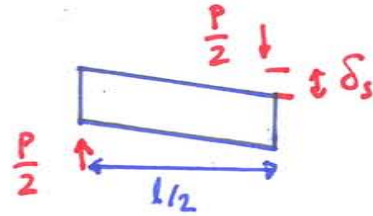
$$= \frac{E_f bt^3}{6} + \frac{E_c bc^3}{12} + \frac{E_f bt}{2} (c+t)^2$$

sandwich structures: typically $E_f \gg E_c^*$ and $c \gg t$

approximate $(EI)_{eq} \approx \frac{E_f b t c^2}{2}$

$\delta_s = ?$

core



$T = G \gamma$

$\frac{P}{A} \propto G \frac{\delta_s}{l}$

$\delta_s = \frac{Pl}{B_2 (AG)_{eq}}$

$(AG)_{eq} = \frac{b(c+t)^2}{c} G_c \approx bc G_c$

$\delta = \delta_b + \delta_s$

$\delta = \frac{2Pl^3}{B_1 E_f b t c^2} + \frac{Pl}{B_2 bc G_c^*}$

AND note:

$G_c^* = C_2 E_s (\rho_c^* / \rho_s)^2$ (foam model)

$C_2 \approx 3/8$

Minimum weight for a given stiffness

- given: face + core materials
 - beam length, width, loading geometry (eq. 3pt bend, B_1, B_2)
- find: face + core thicknesses, $t + c$, + core density ρ_c^* to minimize weight

$$W = 2\rho_f g b t l + \rho_c^* g b c l$$
- solve (P/δ) eqn for ρ_c^* & substitute into weight eqn
- solve $\partial W / \partial c = 0$ & $\partial W / \partial t = 0$ to get t_{opt}, c_{opt}
- substitute t_{opt}, c_{opt} into stiffness eqn (P/δ) to get $\rho_{c, opt}^*$

- note that optimization possible by foam modelling $G_c = C_2 (\rho^*/\rho_s)^2 E_s$

$$\left(\frac{c}{l}\right)_{opt} = 4.3 \left\{ \frac{C_2 B_2}{B_1^2} \left(\frac{\rho_f}{\rho_s}\right)^2 \frac{E_s}{E_f^2} \left(\frac{P}{\delta b}\right) \right\}^{1/5}$$

$$\left(\frac{t}{l}\right)_{opt} = 0.32 \left\{ \frac{1}{B_1 B_2^2 C_2} \left(\frac{\rho_s}{\rho_f}\right)^4 \frac{1}{E_f E_s^2} \left(\frac{P}{\delta b}\right)^3 \right\}^{1/5}$$

$$\left(\frac{\rho_c^*}{\rho_s}\right)_{opt} = 0.59 \left\{ \frac{B_1}{B_2^3 C_2^3} \left(\frac{\rho_s}{\rho_f}\right) \frac{E_f}{E_s^3} \left(\frac{P}{\delta b}\right)^2 \right\}^{1/5}$$

Note: $\frac{W_{face}}{W_{core}} = \frac{1}{4}$ $\frac{\delta b}{\delta} = \frac{1}{3}$ $\frac{\delta_s}{\delta} = \frac{2}{3}$

The design of sandwich panels with foam cores

Table 9.3 Optimum design of a sandwich panel subject to a stiffness constraint

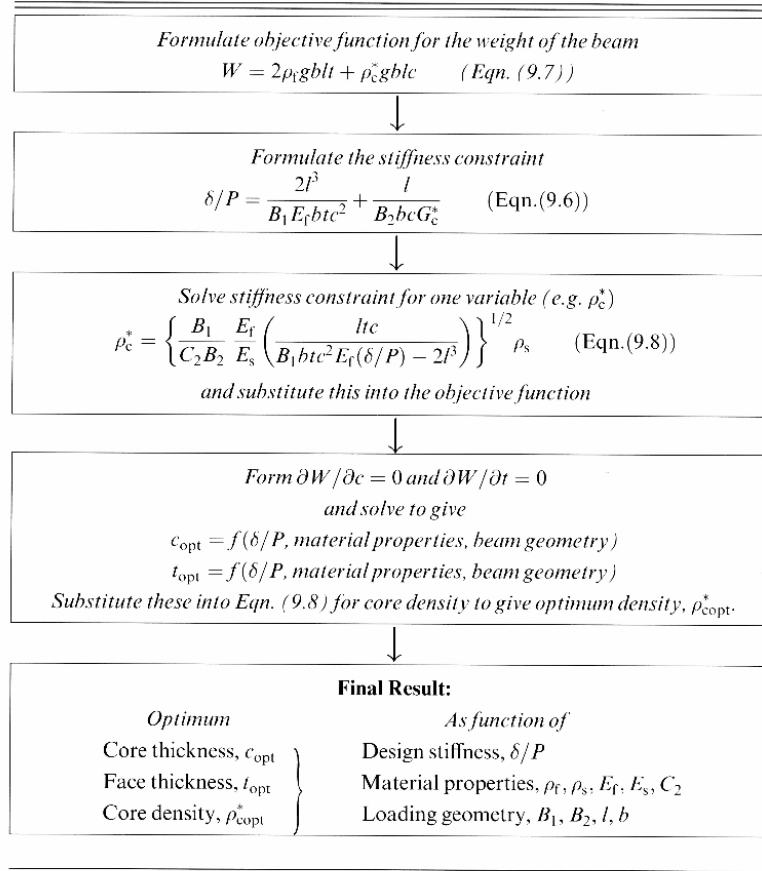


Table 9.4 Optimization analysis for sandwich panels subject to a stiffness constraint

Geometry	W_f/W_c	δ_b/δ	δ_s/δ
Rectangular beam	1/4	1/3	2/3
Circular plate (distributed load over entire plate)	1/4	1/3	2/3
Circular plate (distributed load over radius r)	1/4	1/3	2/3

Comparison with experiments

- All faces with rigid PU foam core
 - $G_c = 0.7 E_s (\rho_c^* / \rho_s)^2$
 - beams designed to have same stiffness, P/G, span l , width, b
 - one set had $\rho_c^* = \rho_c^* \text{opt}$, varied t, c
 - " " " $t = t_{\text{opt}}$, varied ρ_c^*, c
 - " " " $c = c_{\text{opt}}$, varied t, ρ_c^*
 - Confirms min. weight design; similar results with circular sandwich plates
-

Strength of sandwich beams

- stresses in sandwich beams

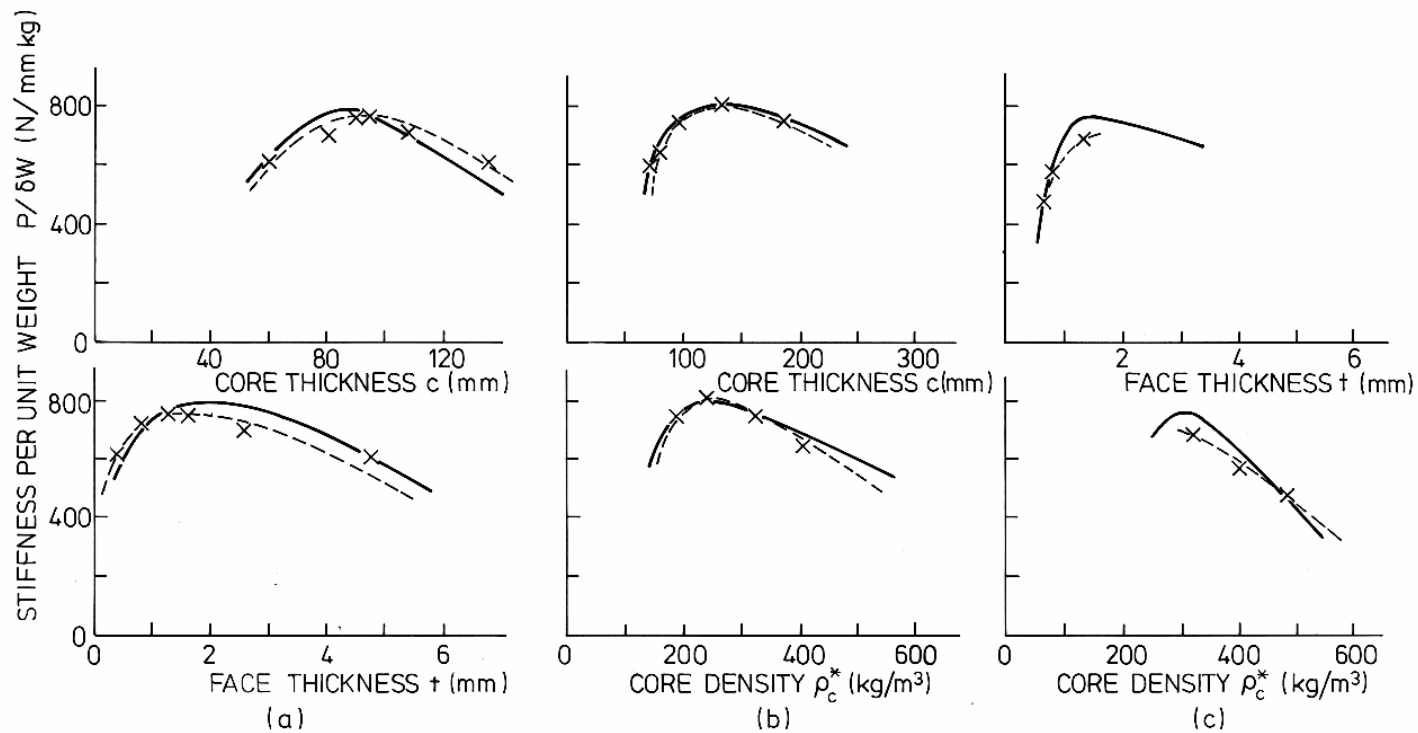
normal stresses

$$\sigma_f = \frac{M y}{(EI)_{eq}} E_f = M \frac{c}{2} \frac{2}{E_f b t c^2} E_f = \frac{M}{b t c}$$

$$\sigma_c = \frac{M y}{(EI)_{eq}} E_c^* = M \frac{c}{2} \frac{2}{E_f b t c^2} E_c^* = \frac{M}{b t c} \frac{E_c^*}{E_f}$$

since $E_c^* \ll E_f$ $\sigma_c \ll \sigma_f \Rightarrow$ faces carry almost all normal stress

Minimum Weight Design



Al faces; Rigid PU foam core

Figures 7, 8, 9: Gibson, L. J. "Optimization of Stiffness in Sandwich Beams with Rigid Foam Cores." *Material Science and Engineering* 67 (1984): 125-35. Courtesy of Elsevier. Used with permission.

• for beam loaded by a concentrated load, P (eq. 3 pt bend)

$M_{max} = \frac{Pl}{B_3}$ e.g. 3 pt bend $B_3 = 4$; cantilever $B_3 = 1$

$$\sigma_f = \frac{Pl}{B_3 b t c}$$

• shear stresses vary parabolically through the cross-section, but if

$E_f \gg E_c^* \quad \& \quad c \gg t \quad \tau_c = \frac{V}{bc}$

V = shear force at section of interest

$$\tau_c = \frac{P}{B_4 b c}$$

$V_{max} = \frac{P}{B_4}$ (eq. 3 pt bend $B_4 = 2$)

Failure modes

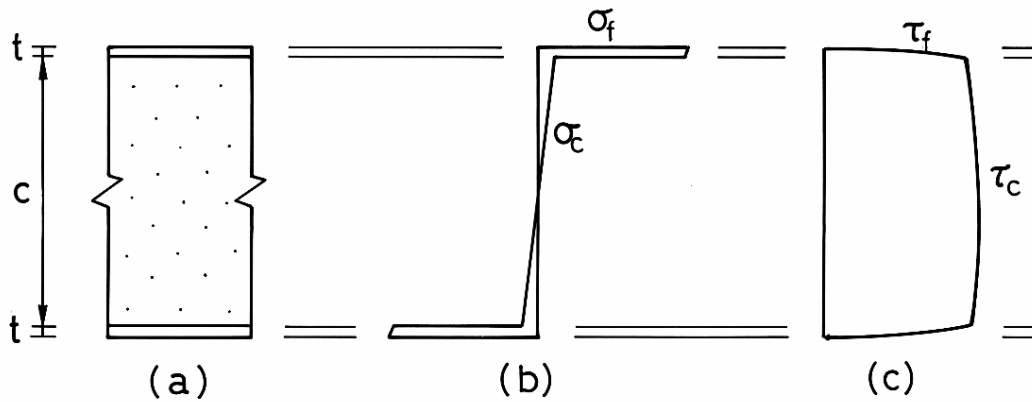
face : - can yield
 - compressive face can buckle locally - "wrinkling"

core ; can fail in shear

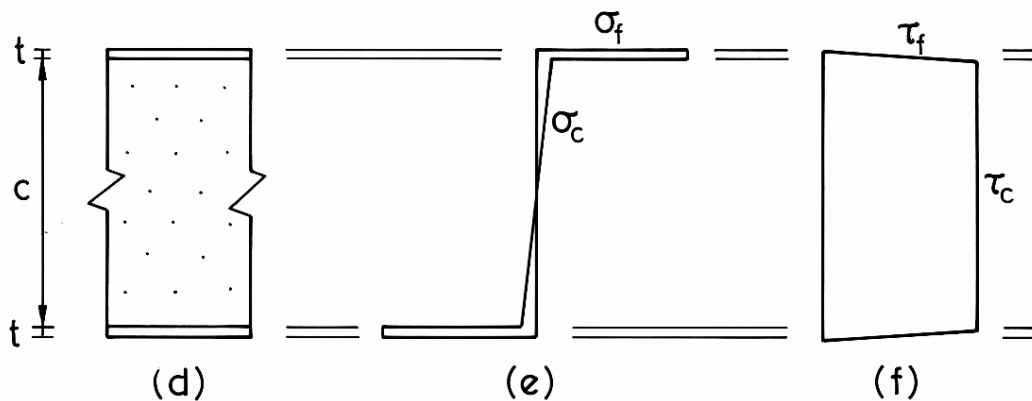
also ; can have debonding + indentation

we will assume perfect bond + load distributed sufficiently to avoid indentation

Stresses

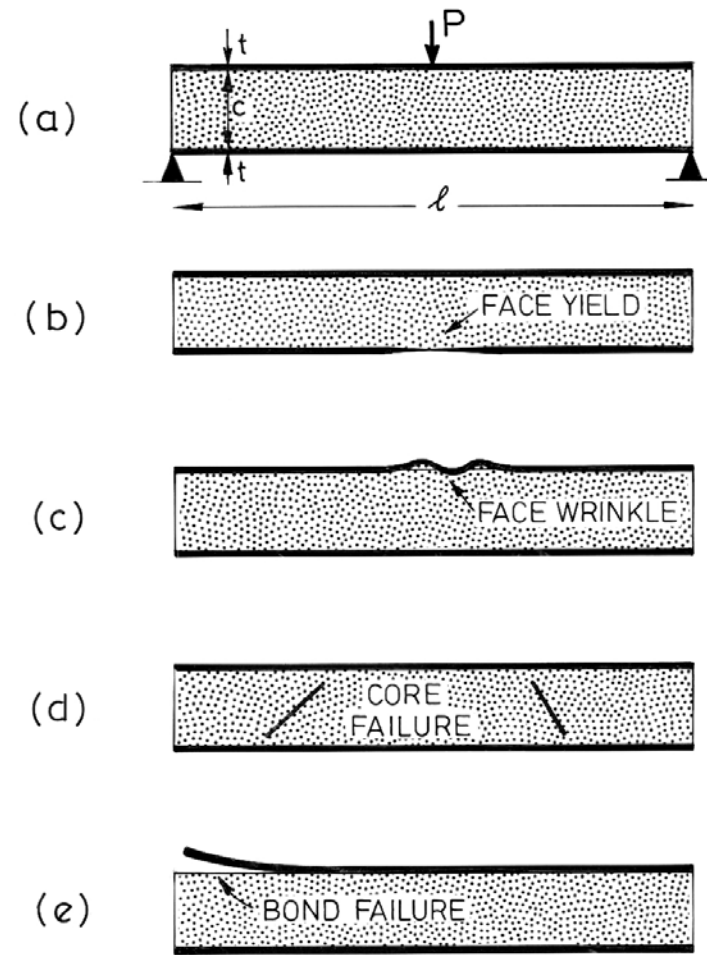


Face: Normal stress
Core: Shear stress



Approximate stress distributions, for:
 $E_c \ll E_f$ and $t \ll c$

Failure Modes



(a) Face yielding

$$\sigma_f = \frac{Pl}{B_s b t c} = \sigma_{yf}$$

(b) Face wrinkling : when normal stress in face = local buckling stress

$$\sigma_{\text{buckling}} = 0.57 E_f^{1/3} E_c^{*2/3} \quad \text{buckling on an elastic foundation}$$

$$E_c^* = (\rho_c^*/\rho_s)^2 E_s$$

$$\sigma_{\text{buckling}} = 0.57 E_f^{1/3} E_s^{2/3} (\rho_c^*/\rho_s)^{4/3}$$

$$\text{Wrinkling occurs when } \sigma_f = \frac{Pl}{B_s b t c} = 0.57 E_f^{1/3} E_s^{2/3} (\rho_c^*/\rho_s)^{4/3}$$

(c) Core shear failure

$$\tau_c = \tau_c^*$$

$$\frac{P}{B_y b c} = C_{11} (\rho_c^*/\rho_s)^{3/2} \sigma_{ys} \quad C_{11} \approx 0.15$$

- dominant failure load is the one that occurs at the lowest load
- how does the failure mode depend on the beam design?
- look at transition from one failure mode to another
- at the transition - two failure modes occur at same load

face yielding: $P_{fy} = B_3 b c (t/l) \sigma_{yf}$

face wrinkling: $P_{fw} = 0.57 B_3 b c (t/l) E_f^{1/3} E_s^{2/3} (\rho_c^* / \rho_s)^{4/3}$

core shear : $P_{cs} = C_{11} B_4 b c \sigma_{ys} (\rho_c^* / \rho_s)^{3/2}$

- face yielding + face wrinkling occur at same load if

$$B_3 b c (t/l) \sigma_{yf} = 0.57 B_3 b c (t/l) E_f^{1/3} E_s^{2/3} (\rho_c^* / \rho_s)^{4/3}$$

$$\text{or } (\rho_c^* / \rho_s) = \left(\frac{\sigma_{yf}}{0.57 E_f^{1/3} E_s^{2/3}} \right)^{3/4}$$

i.e. for given face + core materials, at constant ρ_c^* / ρ_s

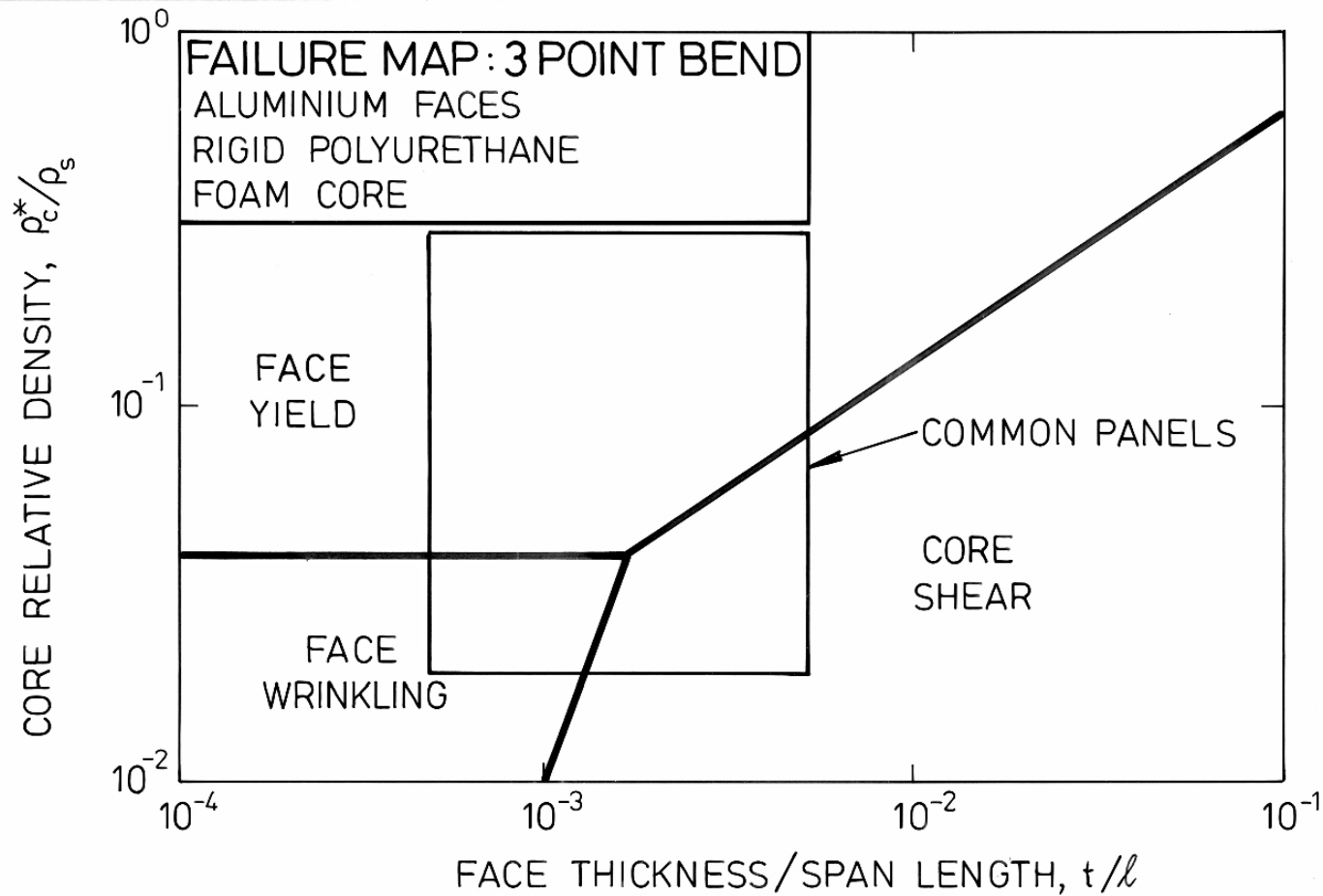
• face yield - core shear $\frac{t}{l} = \frac{C_{11} B_4}{B_3} \left(\frac{\rho_c^*}{\rho_s}\right)^{3/2} \left(\frac{\sigma_{ys}}{\sigma_{yf}}\right)$

• face wrinkling - core shear $\frac{t}{l} = \frac{C_{11} B_4}{0.57 B_3} \frac{\sigma_{ys}}{E_f^{1/3} E_s^{2/3}} \left(\frac{\rho_c^*}{\rho_s}\right)^{1/6}$

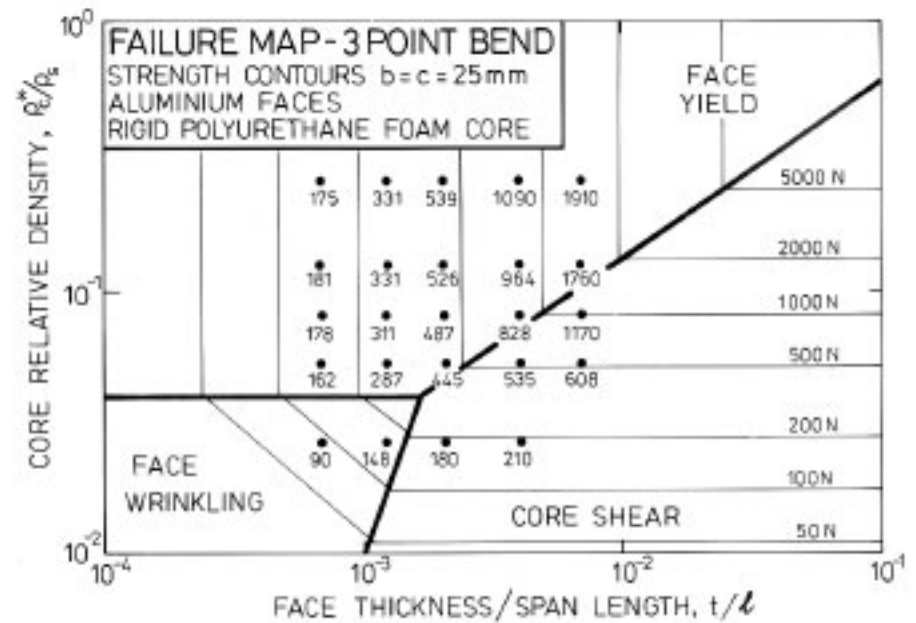
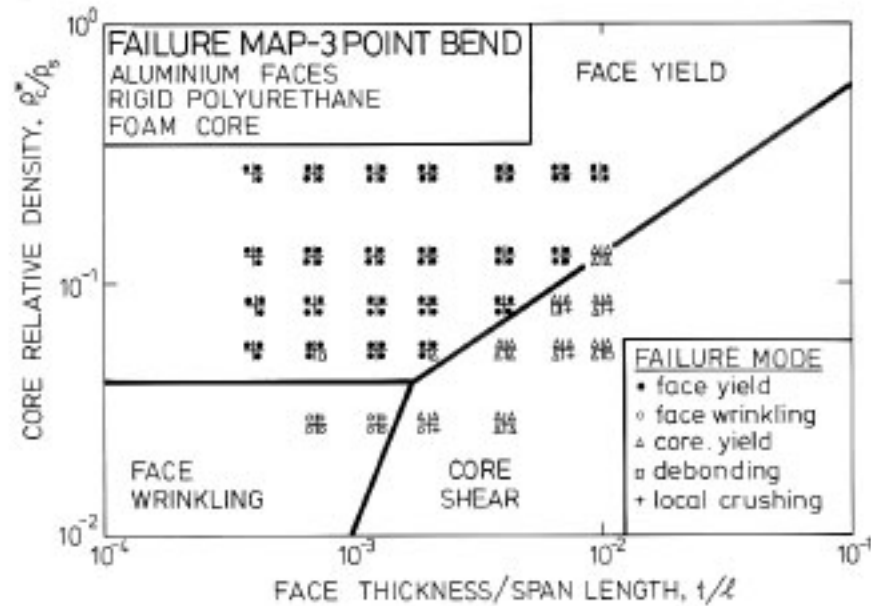
- note: transition eqn only involve constants ($C_{11} B_3 B_4$), material properties (E_f, E_s, σ_{ys}) & $t/l, \rho_c^*/\rho_s$; do not involve core thickness, c
- can plot transition eqn on plot with axes ρ_c^*/ρ_s & t/l

- values of axes chosen to represent realistic values of
 - ρ_c^*/ρ_s - typically 0.02 to 0.3
 - t/l - " $1/2000$ to $1/200 = 0.0005$ to 0.005
- low values of $t/l + \rho_c^*/\rho_s \Rightarrow$ face wrinkling
 - t thin & core stiffness, which acts as elastic foundation, low
- low values t/l , higher values $\rho_c^*/\rho_s \Rightarrow$ transition to face yielding
- higher values of $t/l \Rightarrow$ transition to core failure

Failure Mode Map



Failure Map: Expts



Figures 12 and 13: Triantafillou, T. C., and L. J. Gibson. "Failure Mode Maps for Foam Core Sandwich Beams." *Materials Science and Engineering* 95 (1987): 37-53. Courtesy of Elsevier. Used with permission.

- map shown in figure for three point bending ($B_3 = 4, B_4 = 2$)
- changing loading config. moves boundaries a little, but overall, picture similar
- expts on sandwich beams with Al faces + rigid PU foam cores confirm eqn
- if know b, c - can add contours of failure loads.

Minimum weight design for stiffness + strength: t_{opt}, c_{opt}

given: stiffness $PI\delta$

strength P_0

span l width b

loading configuration (B_1, B_2, B_3, B_4)

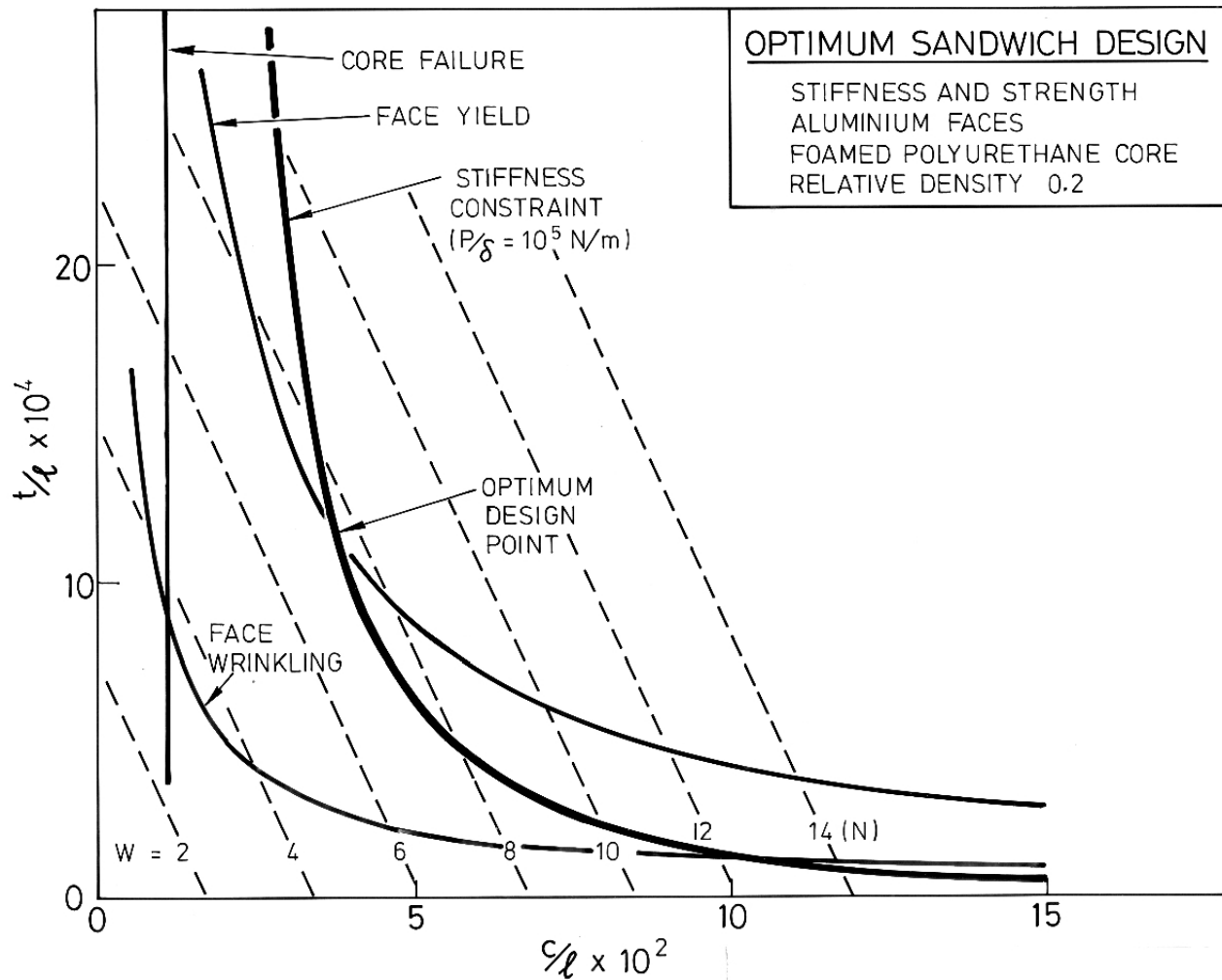
face material (ρ_f, σ_{yf}, E_f)

core material + density ($\rho_s, E_s, \sigma_{ys}, \rho_c^*$)

FIND: face + core thickness, t, c ,
to minimize weight.

- can obtain solution graphically, axes $t/l + c/l$
 - eqn for stiffness constraint + each failure mode plotted
 - dashed lines - contours of weight
 - design limiting constraints are stiffness + force yielding
 - optimum point - where they intersect
 - could add p_c^*/p_s as variable on third axis + create surfaces for stiffness + failure eqn; find optimum in same way
-

- analytical solⁿ possible but cumbersome
- also, values of c/l obtained this way may be unreasonably large - then have to introduce an additional constraint on c/l (e.g. $c/l < 0.1$)



Gibson, L. J., and M. F. Ashby. *Cellular Solids: Structure and Properties*. 2nd ed. Cambridge University Press, © 1997. Figure courtesy of Lorna Gibson and Cambridge University Press.

Minimum weight design : materials

- what are best materials for face + core? (stiffness constraint)
- go back to min. wt. design for stiffness
- can substitute $(\rho_c^2)_{opt}$, t_{opt} , C_{opt} into weight eqn to get min. wt.:

$$W = 3.18 bl^2 \left[\frac{1}{B_1 B_2^2 C_2} \frac{\rho_f \rho_s^4}{E_f E_s^2} \left(\frac{P}{\delta b} \right)^3 \right]^{1/5}$$

• faces: W minimized with materials that minimize $\frac{\rho_f}{E_f}$ (or maximize E_f/ρ_f)

• core: W " " " " " " " " " " " " ρ_s^4/E_s^2 or max. $E_s^{1/2}/\rho_s$

• note: • faces of sandwich loaded by normal stress, axially
 if have solid material loaded axially, want to maximize E/ρ

• core loaded in shear & in the foam, cell edges bend
 if have solid material, loaded as beam in bending + want to minimize weight for a given stiffness, maximize $E^{1/2}/\rho$

• sandwich panels may have face + core same material eq. Al faces Al foam core.
 then want to maximize $E^{3/5}/\rho$ integral polymer face/core "structural polymer foams"

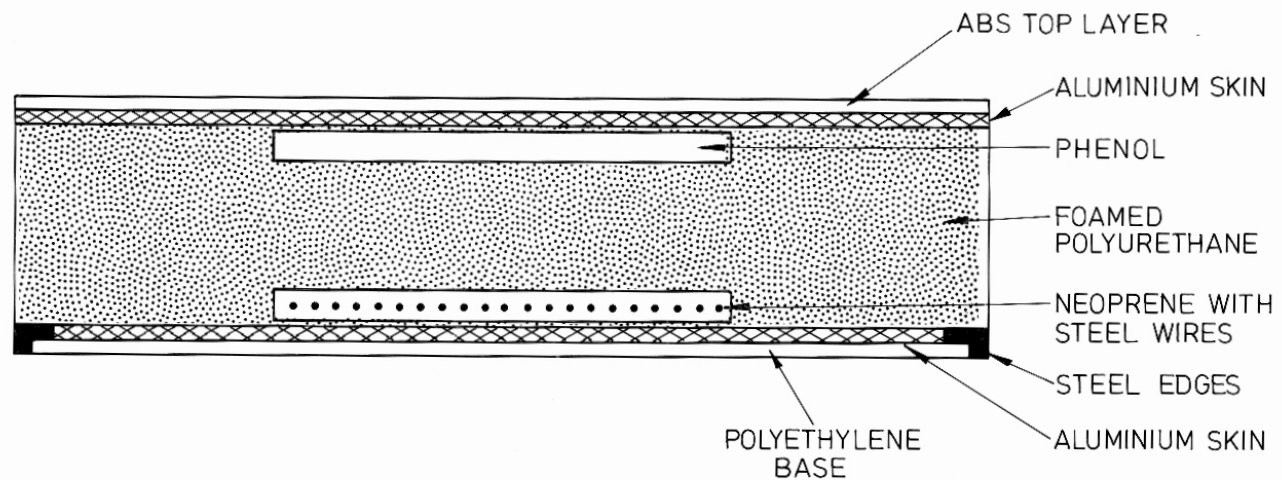
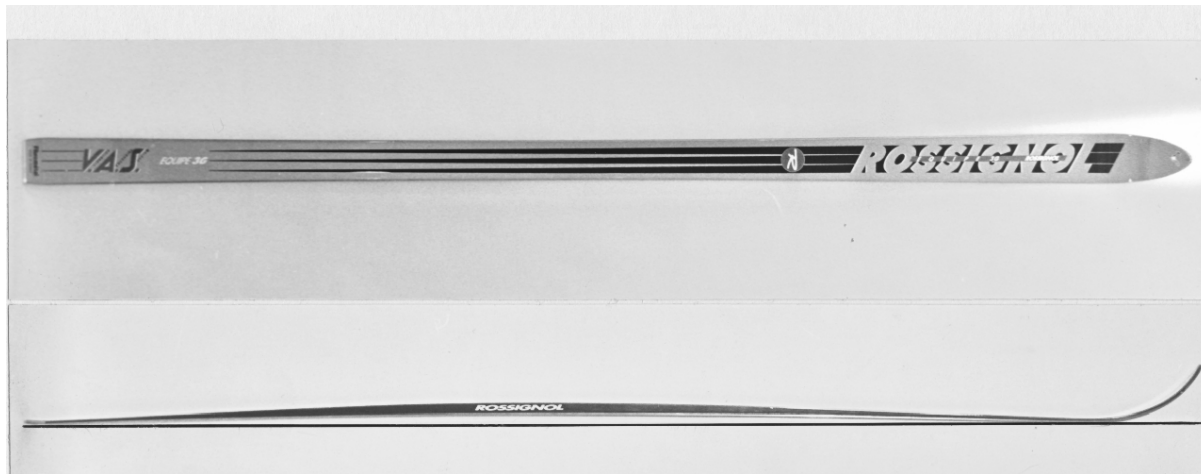
Case study: Downhill ski design

- stiffness of ski gives skier right "feel"
 - too flexible - difficult to control
 - too stiff - skier suspended, as on a plank, between bumps
 - skis designed primarily for stiffness
 - originally skis made from a single piece of wood
 - next - laminated wood skis with denser wood (ash, hickory) on top of lighter wood core (pine, spruce)
-

- modern skis - sandwich beams
 - faces - fiber composites or Al
 - core - honeycombs, foams (eg. rigid PU), balsa
- } Controls stiffness.

- additional materials
 - bottom - layer of polyethylene - reduces friction
 - short strip phenol - screw binding in
 - neoprene strip ~ 300mm long - damping
 - steel edges - better control

Ski Case Study



Ski case study

- properties of face + core materials

	Al	Solid PU	Foam PU
ρ (Mg/m ³)	2.7	1.2	0.53
E (GPa)	70	1.94	0.38
G (GPa)	-	-	0.14

- ski geometry

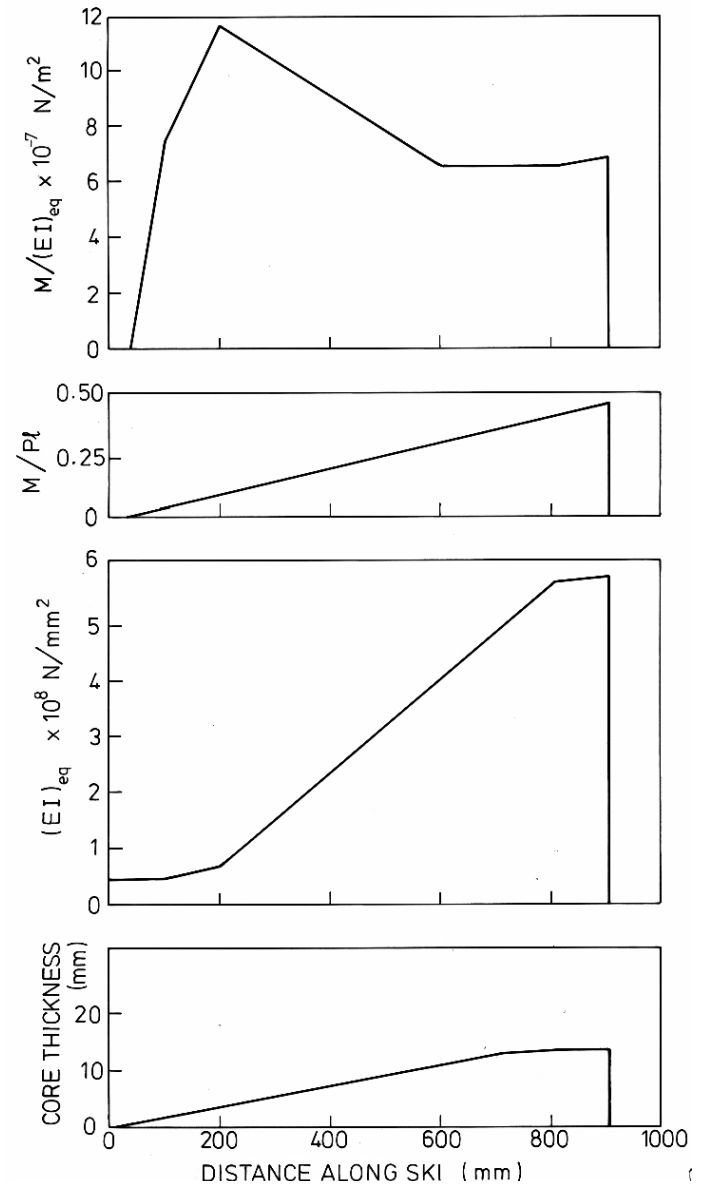
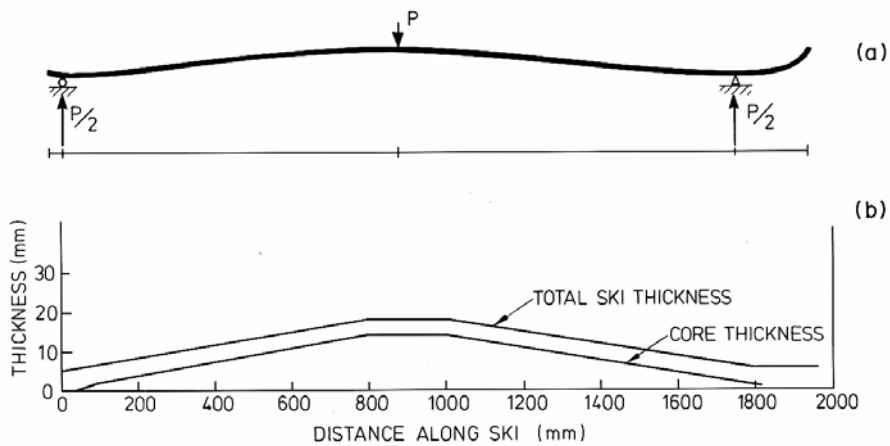
- Al faces constant thickness t

- PU foam core - c varies along length, thickest at centre, where moment highest

- ski cambered

- mass of ski = 1.3 kg (central 1.7 m, neglecting tip + tail)

Ski Case Study



Bending stiffness

- plot c vs. x , distance along ski
- calculated $(EI)_{eq}$ vs x
- calculated Moment applied vs x
- get $M/(EI)_{eq}$ vs x
- can then find bending deflection, $\delta_b = 0.28 P$
- shear deflection found from avg. equiv. shear rigidity

$$\delta_s = \frac{Pl}{(AG)_{eq}} = 0.0045 P$$

- $\delta = \delta_b + \delta_s = 0.29 P$ $P/\delta = 3.5 \text{ N/mm}$ measured $P/\delta = 3.5 \text{ N/mm}$.
 - note current design $\delta_s \ll \delta_b$; at optimum $\delta_s \sim 2\delta_b$ (constant c)
 - can ski be redesigned to give same stiffness, P/δ , at lower weight?
 - if use optimization method described earlier (assuming $c = \text{constant along length}$)

$c_{opt} = 70 \text{ mm}$	mass = 0.31 kg \Rightarrow 75% reduction from current design
$t_{opt} = 0.095 \text{ mm}$	
$\rho_{opt}^* = 29 \text{ kg/m}^3$	
- But this design impractical
 $\Rightarrow c$ too large, t too small

Alternative approach:

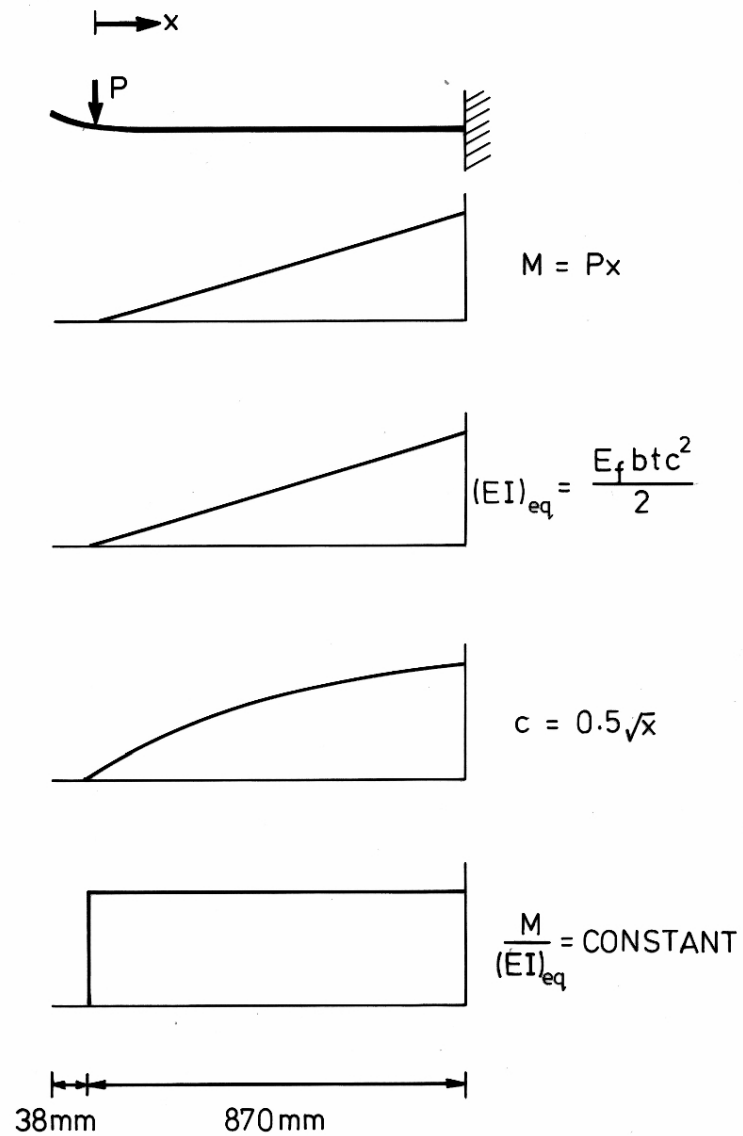
- fix $c = \text{max. value practical under binding}$ & profile c to give constant $M/(EI)_{eq}$ along length of ski (use $c_{max} = 15 \text{ mm}$)
- find values of t, ρ_c^* to minimize wt. for $P/\delta = 3.5 \text{ N/mm}$.
- Moment M varies linearly along the length of the ski
- want $(EI)_{eq}$ to vary linearly, too; $(EI)_{eq} = E_f b t c^2 / 2$
- want $c \propto \sqrt{x}$, distance along length of ski

- half length of ski is 870 mm & $c_{max} = 15 \text{ mm}$

$$c = 15 \left(\frac{x}{870} \right)^{1/2} = 0.51 x^{1/2} \text{ (mm)}$$

- can now do minimum weight analysis with

$$\delta = \frac{P l^3}{2 B_1 E_f b t (c_{max} + t)^2} + \frac{P l}{B_2 C_2 b c_{max} (\rho_c^* / \rho_s)^2 E_s}$$



Gibson, L. J., and M. F. Ashby. *Cellular Solids: Structure and Properties*. 2nd ed. Cambridge University Press, © 1997. Figure courtesy of Lorna Gibson and Cambridge University Press.

- B_1 - corresponds to beam with constant M/EI
- B_2 - cantilever value ($B_2=1$) multiplied by avg. value of c divided by maximum value of c $B_2 = 2/3$
- solve stiffness eq'n for ρ_c^* , substitute into weight eq'n + take $\frac{\partial W}{\partial t} = 0$
- solve for t_{opt} , then ρ_c^*
- find: $C_{max} = 15 \text{ mm}$ $\rho_{c, opt}^* = 163 \text{ kg/m}^3$
 $t_{opt} = 1.03 \text{ mm}$ mass = 0.88 kg \Rightarrow 31% less than current design

Daedalus

- MIT designed + built human powered aircraft (1980s)
- flew 72 miles in ~ 4 hrs. from Crete to Santorini, 1988
- Kanellos Kanellopoulos - Greek bicycle champion pedalled + flew

Mass	68.5 [#]	= 31 kg	propeller: kevlar faces, PS foam core (11' long)
length	29'	= 8.8 m	wing + trailing edge strips kevlar faces / rohacell foam core
Wingspan	112'	= 34 m	tail surface struts: carbon composite faces, Dalsa core

Daedalus



Courtesy of NASA. Image is in the public domain. [NASA Dryden Flight Research Center Photo Collection](#).

Mass = 31 kg

Length = 8.8m

Wingspan = 34m

Propeller blades = 3.4m

Flew 72 miles, from Crete to Santorin, in just under 4 hours

Sandwich panels: propeller, wing and tail trailing edge strips, tail surface struts

Image: MIT Archives

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3.054 / 3.36 Cellular Solids: Structure, Properties and Applications
Spring 2014

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