

**6.231 Dynamic Programming and Optimal Control**  
**Midterm Exam, Fall 2015**  
**Prof. Dimitri Bertsekas**

**Problem 1 (50 points)**

This is a stopping problem, where before stopping is applied, the state of the system evolves according to

$$x_{k+1} = ax_k + bu_k, \quad (1)$$

where the nonzero scalars  $a$  and  $b$  are known. At each period  $k$  where the system has not yet stopped, we have the option of using a control  $u_k$ , incurring a cost  $qx_k^2 + ru_k^2$ , and moving to a new state  $x_{k+1}$  according to Eq. (1), or else stopping (i.e., moving to a special cost-free and absorbing termination state) and incurring a stopping cost  $tx_k^2$  (we may have  $t \neq q$ ). At the final period  $N$ , if not already stopped, we must stop and incur the stopping cost  $tx_N^2$ . We assume that the scalars  $q$ ,  $r$ , and  $t$  are positive.

- (a) Consider first the restricted optimization over policies that never stop, except at time  $N$ , so we obtain a standard linear quadratic problem, whose optimal cost function has the form

$$J_0(x_0) = Kx_0^2,$$

where  $K$  is a positive scalar that depends on  $N$ . Write the Riccati equation that yields  $K$  as well as the steady-state equation that has  $\bar{K}$ , the limit of  $K$  as  $N \rightarrow \infty$ , as its solution. Does the steady-state equation have any other solutions?

- (b) Consider the unrestricted optimization where stopping is also allowed. Write the DP algorithm for this problem.
- (c) Show that for the problem of part (b) there is a threshold value  $\bar{t}$  such that if  $t < \bar{t}$  immediate stopping is optimal at every state, and if  $t > \bar{t}$  continuing at every state  $x_k$  and period  $k$  is optimal. How are the scalars  $\bar{K}$  and  $\bar{t}$  of parts (a) and (c) related?
- (d) State an extension of the result of part (c) for the case of a multidimensional system.

**Problem 2 (50 points)**

Consider a situation involving a blackmailer and his victim. At each stage the blackmailer has a choice of:

- (1) Retiring with his accumulated blackmail earnings.
- (2) Demanding a payment of \$ 1, in which case the victim will comply with the demand (this happens with probability  $p$ , where  $0 < p < 1$ , independently of the past history), or will refuse to pay and denounce the blackmailer to the police (this happens with probability  $1 - p$ ).

Once denounced to the police, the blackmailer loses all of his accumulated earnings and cannot blackmail again. Also, the blackmailer will retire once he reaches accumulated earnings of \$  $n$ , where  $n$  is a given integer that may be assumed very large for the purposes of this problem. The blackmailer wants to maximize the expected amount of money he ends up with.

- (a) Formulate the problem as a stochastic shortest path problem with states  $i = 0, 1, \dots, n$ , plus a termination state,
- (b) Write Bellman's equation and justify that its unique solution is the optimal value function  $J^*(i)$ .
- (c) Use value iteration to show that  $J^*(i)$  is monotonically strictly increasing with  $i$ , and that  $J^*(i) = i$  for all  $i$  larger than a suitable scalar.
- (d) Start policy iteration with the policy where the blackmailer retires at every  $i$ . Derive the sequence of generated policies and the optimal policy. How many iterations are needed for convergence?

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